Energy Efficient River Surface Floating Plastic Trash Cleaning and Oil Soaking Robot

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Abstract

The haphazard industrial waste management of the industries located on the banks of the rivers is seen as a cause of the South Asian region's rivers becoming polluted. Densely populated areas also get polluted from improper management of trash collection by the government. There on the rivers, the Energy Efficient River Surface Floating Plastic Trash Cleaning and Oil Soaking Robot can be used to clean the floating trash from the river surface and can simultaneously soak the oil from the river water. This robot uses river skimmer technology to filter floating trash from the river's edge. The robot's forearms are attached to an oil-absorbing hydrophobic melamine sponge material, which allows the floating robot to absorb oil from river water. The design and construction of this robot for cleaning and soaking up oil are discussed in this paper. The floating trash that comes with the tide is blocked by the hands of this machine. The filtered trash is then collected by a cleated conveyor belt controlled by an Arduino UNO R3 SMD microcontroller. Using a CM30-25NPP-EC1 Capacitive Proximity Sensor, this cleated conveyor belt separates plastic waste. The sensing end of the sensor emits an electrical field from 4mm up to 25mm, in order to detect the plastic trash. Throughout this experiment, the design of hardware orientation and software operation for the robot's operation is explained with construction. The eminent idiosyncrasies can also be used for future skimmer technology based robots, which will be capable of completing tasks with complex functionality.

Keywords

River, Clean, Soak, Oil, Plastic.

Acknowledgements

The authors wish to thank Prof. Dr. Md Mizanur Rahman, the Professor and Head of Department of Mechatronics Engineering, Faculty of Science and Engineering, World University of Bangladesh; for providing us such mental support while working on it.

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Anika Nawar is an undergrad student currently studying BSc in Mechatronics Engineering from Faculty of Science and Engineering, World University of Bangladesh. She is an affiliated engineer of Institutions Mechanical Engineers and acting as Secretary in Industrial Engineering and Operation Management Society World University of Bangladesh Student Chapter since June 2021. Before that she also served as a Director of Media in the same chapter (January 2021-May 2021). In 2019 she participated in a competition organised by IEOM Bangladesh and co-organised by World University of Bangladesh and was a joint champion. She is the Former President of Mechatronics Club, World University of Bangladesh from January 2022 to July 2023. She has done an industrial attachment under Automobile Engineering Course (credit course) as a Service and Maintenance Engineer trainee in Mahindra and Mahindra Ltd, Ranks Workshop Ltd, Rangs Group. She has completed workshops organised by Japan Bangladesh Robotic Society and NASA Solve Bangladesh. Currently she's performing the role of president in Mechatronics Club World University

Proceedings of the 3rd Indian International Conference on Industrial Engineering and Operations Management New Delhi, India, November 2-4, 2023

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